

Game Theory

Dynamic games of complete information

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 - Backwards Induction
 - Stackelberg Model of Duopoly
- 3 Games of imperfect information
- 4 Extensive-form representation
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Motivating Example 1: Grenade Game

- Consider a two-move game between two players.
 - First, player 1 decides whether to give \$1000 to player 2.
 - Second, **after observing** the choice of player 1, player 2 chooses whether to explode a grenade that will kill both of them.

Player 2 can threaten player 1 by saying “Give the money to me, otherwise I will explode the grenade to kill you!”

- Question:
 - What should player 1 do in the first place?
 - Is player 2's threat credible to player 1?
 - What is the outcome of this simple game?

Motivating Example 2: The Farmer and The Snake

- On a winter evening, a farmer found a snake frozen with cold.
 - The farmer wanted to save the snake, which would make himself happy.
 - But he was worried if the snake would bite him after it was saved.
 - Believing that the snake would be grateful, the farmer saved it.
 - However, when the snake was recovered, it bit and killed the farmer immediately.
- Question: Why shouldn't the farmer save the snake?

Introduction

- The two examples differ from the games that we have studied before: players take actions **sequentially**, rather than simultaneously.
- These are examples of **dynamic games** (动态博弈).
- The central issue of dynamic games is **credibility** (可信性).
- We want to study dynamic games of complete information.
 - Dynamic: sequential choice or repeated play
 - Complete information: each player's **payoff function is common knowledge** among all players

Introduction

- Two types of dynamic games of complete information (完全信息):
 - ① Dynamic games of complete and perfect information (完美信息)
 - ② Dynamic games of complete and imperfect information (不完美信息)
- In static games of complete information, we use normal-form (标准式) representation to describe a game.
- Now we use extensive-form (扩展式) representation for dynamic games.
- In particular, we will draw game trees (博弈树).

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Games of Perfect Information

Consider a two-player and two-stage game.

- Player 1 chooses an action L or R .
- Player 2 observes player 1's action and then chooses an action L' or R' .
- Each path (a combination of two actions) in the following tree is followed by two payoffs: the first for player 1 and the second for player 2.

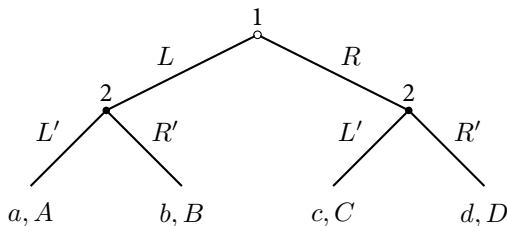


Figure: Extensive-form representation using a game tree

Games of Perfect Information

- The above game is an example of dynamic games of complete and perfect information.
- This type of games takes the following form:
 - Player 1 chooses an action a_1 from the feasible set A_1 ;
 - Player 2 observes a_1 and then chooses an action a_2 from the feasible set A_2 ;
 - Payoffs are $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$.
- Note that
 - A_2 may depend on the action a_1 , i.e., $A_2(a_1)$.
 - Some action a_1 may even end the game, so that $A_2(a_1)$ is an empty set (i.e., no choice of player 2).

Games of Perfect Information

In Example 1:

- $A_1 = \{L, R\}$, where L = “give \$1000” and R = “don’t give”;
- $A_2(L) = A_2(R) = \{L', R'\}$, where L' = “explode” and R' = “don’t explode”.

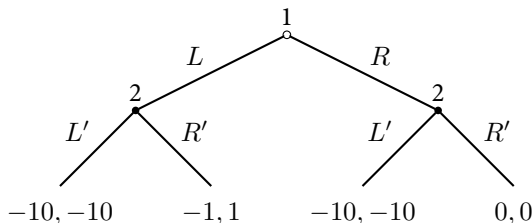


Figure: Game tree for Example 1

Games of Perfect Information

In Example 2:

- $A_1 = \{L, R\}$, where L = “save” and R = “don’t save”;
- $A_2(L) = \{L', R'\}$, where L' = “bite” and R' = “don’t bite”.

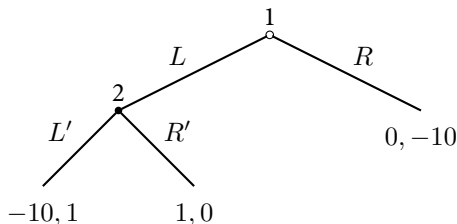


Figure: Game tree for Example 2

Games of Perfect Information

- Some key features of dynamic games of complete and perfect information:
 - 1 the moves occur **in sequence**;
 - 2 all previous moves are **observed** before the next move is chosen;
 - 3 the players' **payoffs** from each combination of moves are **common knowledge**.
- How to solve this type of games?
- We use **backwards induction** (逆向归纳).

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Backwards Induction

- In the **second stage**, player 2 observes the action (say a_1) chosen by player 1 in the first stage, and then chooses an action by solving

$$\max_{a_2 \in A_2} u_2(a_1, a_2).$$

- Assume this optimization problem has a **unique** solution, denoted by $R_2(a_1)$. This is player 2's best response to player 1's action a_1 .
- For example, $R_2(L) = R'$ and $R_2(R) = L'$.

Backwards Induction

- In the **first stage**, knowing player 2's best response, player 1's problem becomes

$$\max_{a_1 \in A_1} u_1(a_1, R_2(a_1)).$$

- Assume it also has a **unique** solution, denoted by a_1^* .
- For example, $a_1^* = R$ and $R_2(a_1^*) = L'$.
- We call $(a_1^*, R_2(a_1^*))$ the **backwards-induction outcome** (逆向归纳的结果) of the game.

Backwards Induction

- In Example 1:
 - $R_2(L) = R_2(R) = R'$
 - $a_1^* = R$ and $R_2(a_1^*) = R'$
 - The backwards-induction outcome is (R, R') .
- In Example 2:
 - $R_2(L) = L'$
 - $a_1^* = R$
 - The backwards-induction outcome is R .

Backwards-induction outcome vs. Nash equilibrium

What is the relationship between a backwards-induction outcome and a Nash equilibrium?

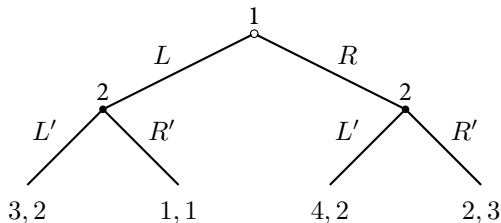
- If both players choose their actions simultaneously, then the Nash equilibrium (a_1^{**}, a_2^{**}) is the intersection of two best responses, i.e., it solves

$$a_1^{**} = R_1(a_2^{**}), \quad a_2^{**} = R_2(a_1^{**}).$$

- In the backwards-induction outcome, a_1^* is determined by maximizing $u_1(a_1, R_2(a_1))$, and we let $a_2^* = R_2(a_1^*)$.
- Since a_1^* may not maximize $u_1(a_1, a_2^*)$, the Nash equilibrium (a_1^{**}, a_2^{**}) can be different from the backwards-induction outcome (a_1^*, a_2^*) .

Backwards-induction outcome vs. Nash equilibrium (Cont.)

- Consider the following game:



- $R_2(L) = L'$ and $R_2(R) = R'$
- The backwards-induction outcome is (L, L') .

Backwards-induction outcome vs. Nash equilibrium (Cont.)

- Suppose both players choose actions simultaneously, then they play the following game:

		Player 2	
		L'	R'
Player 1	L	3, 2	1, 1
	R	4, 2	2, 3

- The Nash equilibrium is (R, R') , which differs from the backwards-induction outcome (L, L') .

The backwards-induction outcome in a dynamic game could be different from the Nash equilibrium of the corresponding game played simultaneously.

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Stackelberg Model of Duopoly

Consider a dominant firm moving first and a follower moving second.

- The game is played as follows:
 - Firm 1 chooses a quantity $q_1 \geq 0$.
 - Firm 2 observes q_1 and then chooses a quantity $q_2 \geq 0$.
 - The payoff of firm i is the profit

$$\pi_i(q_1, q_2) = q_i[P(Q) - c],$$

where $Q = q_1 + q_2$ and

$$P(Q) = \begin{cases} a - Q, & \text{if } Q < a; \\ 0, & \text{if } Q \geq a. \end{cases}$$

- How to find the backwards-induction outcome?

Stackelberg Model of Duopoly

- First, find the best response function $R_2(q_1)$ for firm 2, i.e., for any given q_1 , find q_2 that solves

$$\max_{q_2 \geq 0} \pi_2(q_1, q_2),$$

where

$$\pi_2(q_1, q_2) = \begin{cases} q_2(a - q_1 - q_2 - c), & \text{if } q_1 + q_2 < a; \\ -cq_2, & \text{if } q_1 + q_2 \geq a. \end{cases}$$

- Then we have

$$R_2(q_1) = \begin{cases} \frac{a-c-q_1}{2}, & \text{if } q_1 < a - c; \\ 0, & \text{if } q_1 \geq a - c. \end{cases}$$

- $R_2(q_1)$ is the same as that in the Cournot model.

Stackelberg Model of Duopoly

- Second, firm 1 knows $R_2(q_1)$ and solves

$$\max_{q_1 \geq 0} \pi_1(q_1, R_2(q_1)),$$

where

$$\pi_1(q_1, R_2(q_1)) = \begin{cases} q_1 \left[a - q_1 - \frac{a - q_1 - c}{2} - c \right], & \text{if } q_1 < a - c; \\ q_1 [a - q_1 - c], & \text{if } a - c \leq q_1 < a; \\ -cq_1, & \text{if } q_1 \geq a. \end{cases}$$

Stackelberg Model of Duopoly

- Clearly, for $q_1 > a - c$, firm 1's profit is always negative.
- Thus we only need to solve

$$\max_{a-c > q_1 \geq 0} q_1 \left[a - q_1 - \frac{a - q_1 - c}{2} - c \right] = \max_{a-c > q_1 \geq 0} \left[\frac{1}{2} q_1 (a - q_1 - c) \right]$$

which leads to the following first-order condition

$$a - c - 2q_1 = 0.$$

- The optimal choice of firm 1 is

$$q_1^* = \frac{a - c}{2}.$$

Stackelberg Model of Duopoly

- The quantity chosen by firm 2 is

$$q_2^* = R_2(q_1^*) = \frac{a - c}{4}.$$

- The market price is

$$P^* = a - q_1^* - q_2^* = c + \frac{a - c}{4}.$$

- Firms' profits and the total profit are

$$\pi_1^* = \frac{(a - c)^2}{8}, \pi_2^* = \frac{(a - c)^2}{16}, \text{ and } \Pi^* = \frac{3(a - c)^2}{16}.$$

Cournot model vs. Stackelberg model

Variable	Cournot Model	Stackelberg Model
q_1^*	$\frac{a-c}{3}$	$\frac{a-c}{2}$
q_2^*	$\frac{a-c}{3}$	$\frac{a-c}{4}$
π_1^*	$\frac{(a-c)^2}{9}$	$\frac{(a-c)^2}{8}$
π_2^*	$\frac{(a-c)^2}{9}$	$\frac{(a-c)^2}{16}$
Π^*	$\frac{2(a-c)^2}{9}$	$\frac{3(a-c)^2}{16}$
P^*	$c + \frac{a-c}{3}$	$c + \frac{a-c}{4}$

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Games of Imperfect Information

- Consider the following simple two-stage game:
 - Players 1 and 2 simultaneously choose actions a_1 and a_2 from the feasible sets A_1 and A_2 , respectively.
 - Players 3 and 4 observe the outcome of the first stage (a_1, a_2) and then simultaneously choose actions a_3 and a_4 from the feasible sets A_3 and A_4 , respectively.
 - Payoffs are $u_i(a_1, a_2, a_3, a_4)$ for $i = 1, 2, 3, 4$.
- This game differs from the two-stage game with perfect information, since there are **simultaneous moves within each stage**.

Games of Imperfect Information

- We solve this game by using the idea of backwards induction.
- For each given (a_1, a_2) , players 3 and 4 try to find the **Nash equilibrium** in stage 2.
- Assume the second-stage game has a unique Nash equilibrium

$$(a_3^*(a_1, a_2), a_4^*(a_1, a_2)).$$

- Then, player 1 and player 2 play a simultaneous-move game with payoffs

$$u_i(a_1, a_2, a_3^*(a_1, a_2), a_4^*(a_1, a_2)), \text{ for } i = 1, 2.$$

Games of Imperfect Information

- Suppose (a_1^*, a_2^*) is the unique **Nash equilibrium** of this simultaneous-move game.
- Then

$$(a_1^*, a_2^*, a_3^*(a_1^*, a_2^*), a_4^*(a_1^*, a_2^*))$$

is the **subgame-perfect outcome** (子博弈精炼结果) of the two-stage game.

Bank Runs

- Two investors have each deposited \$5 millions with a bank. The bank has invested these deposits in a long-term project.
- If the bank is forced to liquidate its investment before the project matures, a total of \$8 millions can be recovered.
- If the bank allows the investment to reach maturity, the project will pay out a total of \$16 millions.
- There are two dates at which the investors can make withdrawals at the bank: Date 1 is before the bank's investment matures and Date 2 is after.
- Suppose there is no discounting.

Bank Runs

- Players' payoffs in date 1:

	Withdraw	Don't
Withdraw	4, 4	5, 3
Don't	3, 5	next stage

- Players' payoffs in date 2:

	Withdraw	Don't
Withdraw	8, 8	11, 5
Don't	5, 11	8, 8

Bank Runs

We work backwards:

- At date 2, in the unique Nash equilibrium, both withdraw and each obtains \$8.
- At date 1, they play the following game:

	Withdraw	Don't
Withdraw	4, 4	5, 3
Don't	3, 5	8, 8

- There are 2 pure-strategy Nash equilibria of this game:
 - Both withdraw and each obtains \$4;
 - Both don't and each obtains \$8.

Bank Runs

- There are 2 subgame-perfect outcomes of the original two-stage game:
 - ① Both withdraw at date 1 to obtain \$4 \rightarrow the case of bank run
 - ② Both don't withdraw at date 1 but do at date 2, and obtain \$8
- Although there are two possible subgame-perfect outcomes, only the second one is efficient.
- This model does not predict when bank runs will occur, but does show that they can occur as an equilibrium outcome.

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Normal-form Representation of Games

In static games, we consider normal-form representation to describe a game.

Definition

The **normal-form representation** of a game specifies

- 1 the players in the game;
- 2 the strategies available to each player;
- 3 the payoff received by each player for each combination of strategies that could be chosen by the players.

Extensive-form Representation of Games

In dynamic games, we need to use extensive-form representation.

Definition

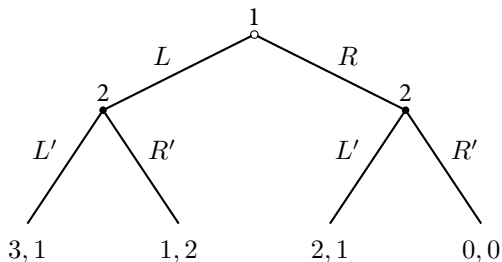
The **extensive-form** (扩展式) **representation** of a game specifies:

- (1) the players in the game;
- (2a) when each player has the move;
- (2b) what each player can do at each of his or her opportunities to move;
- (2c) what each player knows at each of his or her opportunities to move;
- (3) the payoffs received by each player for each combination of moves that could be chosen by the players.

Note that (2a)–(2c) describe **strategies** (策略) of each player in detail.

Extensive-form Representation of Games

- We use game trees for extensive-form games.
- Example 3:



Extensive-form Representation of Games

- In Example 3, the game tree begins with a **decision node** (节点) for player 1, which is also the **initial node** (初始节点) of the game.
- After player 1's choice (L or R) is made, player 2's decision node is reached. And player 2 needs to decide whether to choose L' or R' .
- A **terminal node** (终止节点) is reached after player 2's move (i.e., the game ends), and payoffs of players are realized.

Information Set

- A dynamic game of complete and perfect information is a game in which the players move in sequence, all previous moves are observed before the next move is chosen, and payoffs are common knowledge.
- Such games can be easily represented by a game tree.
- For games with imperfect information, some previous moves are **not observed** by the player with the current move.
- To present this kind of ignorance of previous moves and to describe what each player knows at each of his/her move, we introduce the notion of a player's **information set** (信息集).

Information Set

Definition

An **information set** (信息集) for a player is a **collection of decision nodes** satisfying:

- (i) The player needs to move at every node in the information set.
 - (ii) When the play of the game reaches a node in the information set, the player with the move **does not know which node in the set has (or has not) been reached**.
-
- (ii) implies that the player must have the **same set of feasible actions** at each decision node in an information set;
 - Otherwise the player could infer from the set of actions available that some node(s) had or had not been reached.

Information Set

- In an extensive-form game, a collection of decision nodes, which constitutes an information set, is connected by a **dotted line**.
- We can use information set to differentiate perfect and imperfect information.
- A game is of **perfect information** (完美信息) if every information set is a singleton, and of **imperfect information** (不完美信息) if there is at least one non-singleton information set.

Information Set

- Let's consider a two-player simultaneous-move (static) game as follows:
 - 1 Player 1 chooses $a_1 \in A_1$;
 - 2 Player 2 does not observe player 1's move but chooses an $a_2 \in A_2$;
 - 3 Payoffs are $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$.
- We need an information set to describe player 2's ignorance of player 1's actions.
- The above static game of complete information can be represented as a dynamic game of complete but imperfect information.

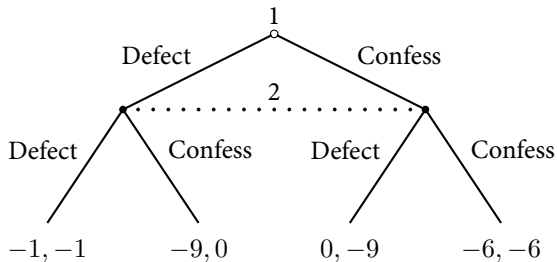
Information Set

- Example 4: Prisoners' Dilemma
- The normal-form representation is

		Prisoner 2	
		Defect	Confess
Prisoner 1	Defect	$-1, -1$	$-9, 0$
	Confess	$0, -9$	$-6, -6$

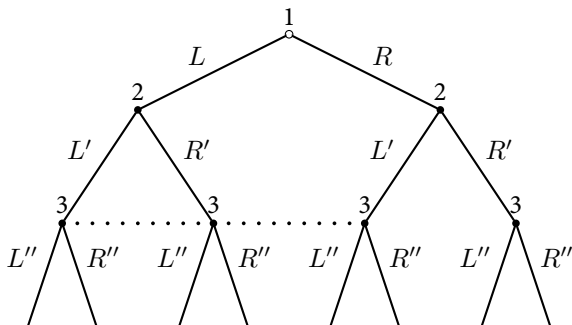
Information Set

The extensive-form representation of Example 4 is:



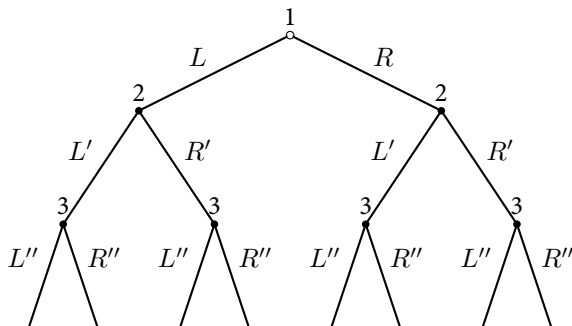
Information Set

In the following Example 5, Player 3 has a non-singleton information set and a singleton information set.



Information Set

In the following Example 6, Player 3 has 4 singleton information sets.



Strategy

Definition

A **strategy** (策略) for a player is a **complete plan of actions**. It specifies a feasible action for the player in every contingency in which the player might be called on to act.

- An equivalent definition: A player's **strategy** is a function which assigns an action to each information set (**not** each decision node) belonging to the player.
- An action and a strategy do not make a big difference in static games, while they do in dynamic games.

Strategy

In Example 3:

- Player 1 has 2 actions (and also 2 strategies): L and R .
- Player 2 has 2 actions: L' and R' , but 4 strategies:

$$(L', L'); (L', R'); (R', L'); (R', R').$$

- For example, the strategy (L', R') means:
 - if player 1 plays L , then player 2 plays L' ;
 - if player 1 plays R , then player 2 plays R' .

Strategy

In Example 4:

- Both players have two actions and also two strategies: Defect and Confess.

In Example 5:

- Player 1 has two strategies: L and R .
- Player 2 has four strategies:

$$(L', L'); (L', R'); (R', L'); (R', R').$$

- Player 3 has four strategies

$$(L'', L''); (L'', R''); (R'', L''); (R'', R'').$$

Strategy

In Example 6:

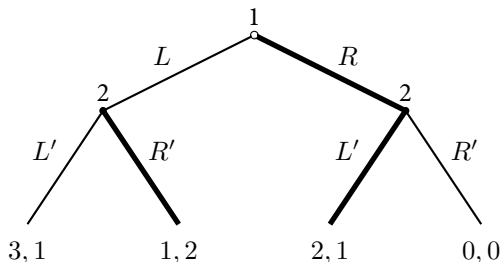
- Player 3 has 16 strategies.
- For instance, the strategy (L'', R'', R'', L'') means:
 - if player 1 plays L and player 2 plays L' , then player 3 plays L'' ;
 - if player 1 plays L and player 2 plays R' , then player 3 plays R'' ;
 - if player 1 plays R and player 2 plays L' , then player 3 plays R'' ;
 - if player 1 plays R and player 2 plays R' , then player 3 plays L'' .

Strategy

- In the Cournot model of duopoly, firm i 's action and strategy is the same, i.e., $q_i \geq 0$.
- In the Stackelberg model, the action and strategy for firm 1 (the leader) is again $q_1 \geq 0$.
- How about firm 2 (the follower)? How many information sets does firm 2 have?
- Firm 2's action is $q_2 \geq 0$, but its strategy is $q_2(q_1) \geq 0$ for any $q_1 \geq 0$.

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Problems of NE



- There are two NE: $(L, R'R')$ and $(R, R'L')$.
- $(L, R'R')$ has a problem: No matter which action is chosen by Player 1, player 2 must choose L' at the right node.
- Interpretation: Player 2 tells player 1: if you choose R , I will choose R' (threat), then each of us will get 0.
- This threat is **non-credible**: Player 1 should not believe that player 2 will choose R' after observing R .

Subgame-Perfect Nash Equilibrium

Definition

A **subgame** (子博弈) in an extensive-form game

- (a) begins at a decision node n that is a **singleton information set** (but is not the game's initial node);
- (b) includes **all** the decision and terminal nodes following node n in the game tree (but no nodes that do not follow n);
- (c) **does not cut any information sets** (i.e., if a decision node n' follows n in the game tree, then all other nodes in the information set containing n' must also follow n , and so must be included in the subgame).

Subgame-Perfect Nash Equilibrium

- Example 3 has 2 subgames.
- Example 4 has no subgame (since player 2's decision nodes are in the same non-singleton information set).
- Example 5 has only 1 subgame, beginning at player 3's decision node following R and R' . (The subtrees beginning at player 2's decision nodes violate (c)).
- Example 6 has 6 subgames.

Subgame-Perfect Nash Equilibrium

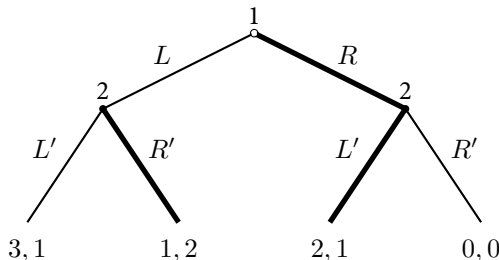
Definition (Selten, 1965)

A Nash equilibrium is **subgame-perfect** (子博弈精炼) if the players' strategies constitute a Nash equilibrium in every subgame.

- It can be shown that any finite dynamic game of complete information has a subgame-perfect Nash equilibrium (子博弈精炼均衡), perhaps in mixed-strategies.
- To find subgame-perfect Nash equilibria,
 - we first need to find Nash equilibria in each subgame,
 - then use backwards-induction to solve for the whole game.

Subgame-Perfect Nash Equilibrium

- In Example 1, there are two subgames: in the left subgame, the Nash equilibrium involves the player 2 choosing R' ; in the right subgame, the Nash equilibrium involves the player 2 choosing L' .
- The subgame-perfect Nash equilibrium is $(R, (R', L'))$.
- We can use thick lines to represent the equilibrium paths.



Subgame-Perfect Nash Equilibrium

- Subgame-perfect Nash equilibrium is closely related to two previous concepts:
 - ① backwards-induction outcome
 - ② subgame-perfect outcome
- What's the difference between an equilibrium and an outcome?
- An equilibrium is a collection of players' **strategy profiles**, while an outcome is a collection of players' **actions**.

Subgame-Perfect Nash Equilibrium

- Consider the following two-stage game of complete and perfect information:
 - 1 Player 1 chooses an action $a_1 \in A_1$;
 - 2 Player 2 observes a_1 and then chooses an action $a_2 \in A_2$;
 - 3 Payoffs are $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$.
- The best response $R_2(a_1)$ solves $\max_{a_2 \in A_2} u_2(a_1, a_2)$.
- a_1^* solves $\max_{a_1 \in A_1} u_1(a_1, R_2(a_1))$.

Subgame-Perfect Nash Equilibrium

- The backwards-induction outcome is $(a_1^*, R_2(a_1^*))$.
- The subgame-perfect Nash equilibrium is $(a_1^*, R_2(\cdot))$.
- Note that $R_2(a_1^*)$ is an action, while $R_2(\cdot)$ is a strategy for player 2.
- In Example 1:
 - (R, L') is the backwards-induction outcome, while $(R, (R', L'))$ is the subgame-perfect Nash equilibrium.
- In the Stackelberg model:
 - The backwards-induction outcome is (q_1^*, q_2^*) , where $q_1^* = \frac{a-c}{2}$ and $q_2^* = \frac{a-c}{4}$, while the subgame-perfect Nash equilibrium is $(q_1^*, R_2(q_1))$, where $R_2(q_1) = \frac{a-c-q_1}{2}$.

Subgame-Perfect Nash Equilibrium

- Consider the following two-stage game of complete but imperfect information:
 - Players 1 and 2 simultaneously choose actions a_1 and a_2 from the feasible sets A_1 and A_2 , respectively.
 - Players 3 and 4 observe the outcome of the first stage (a_1, a_2) and then simultaneously choose actions a_3 and a_4 from the feasible sets A_3 and A_4 , respectively.
 - Payoffs are $u_i(a_1, a_2, a_3, a_4)$ for $i = 1, 2, 3, 4$.
- For each given (a_1, a_2) , players 3 and 4 play the Nash equilibrium in stage 2

$$(a_3^*(a_1, a_2), a_4^*(a_1, a_2)).$$

Subgame-Perfect Nash Equilibrium

- Then, player 1 and player 2 play a simultaneous-move game with payoffs

$$u_i(a_1, a_2, a_3^*(a_1, a_2), a_4^*(a_1, a_2)), i = 1, 2$$

- Suppose (a_1^*, a_2^*) is the unique Nash equilibrium in stage 1.
- Then the subgame-perfect outcome is

$$(a_1^*, a_2^*, a_3^*(a_1^*, a_2^*), a_4^*(a_1^*, a_2^*)).$$

- The subgame-perfect Nash equilibrium is

$$(a_1^*, a_2^*, a_3^*(a_1, a_2), a_4^*(a_1, a_2)).$$

Nash Equilibrium vs. Subgame-Perfect Nash Equilibrium

- A Nash equilibrium may not be subgame-perfect.
- In Example 3, the normal-form representation is

		Player 2			
		(L', L')	(L', R')	(R', L')	(R', R')
Player 1	L	3, 1	3, 1	1, 2	1, 2
	R	2, 1	0, 0	2, 1	0, 0

- Two Nash equilibria: $(L, (R', R'))$ and $(R, (R', L'))$
- Only one subgame-perfect Nash equilibrium: $(R, (R', L'))$

Nash Equilibrium vs. Subgame-Perfect Nash Equilibrium

- The Nash equilibrium $(R, (R', L'))$ is subgame-perfect, because R' and L' are the optimal strategies in the left and right subgames, respectively, where player 2 is the only player.
- On the other hand, the Nash equilibrium $(L, (R', R'))$ is not subgame-perfect, because when player 1 chooses R , R' is not optimal to player 2 in the right subgame, i.e., R' is not a Nash equilibrium in that subgame.
- One can think the strategy (R', R') by player 2 as a threat to player 1.

Nash Equilibrium vs. Subgame-Perfect Nash Equilibrium

- Nash equilibria that rely on non-credible threats or promises can be **eliminated** by the requirement of subgame perfection.
- Subgame-perfect Nash equilibrium is a refinement of Nash equilibrium, i.e.,

$$\{\text{Subgame-perfect Nash equilibria}\} \subseteq \{\text{Nash equilibria}\}$$

Application: Sequential Bargaining Game

- Suppose players 1 and 2 are bargaining over one dollar.
- They discount payoffs received a period later by a discount factor δ , where $0 < \delta < 1$.
- Consider the following three-period bargaining game:
 - (1a) In the first period, player 1 proposes $s_1(1)$ for himself and $s_2(1)$ for player 2.
 - (1b) Player 2 either accepts the offer to end the game or rejects the offer to continue the game.
 - (2a) In the second period, player 2 proposes $s_1(2)$ for player 1 and $s_2(2)$ for himself.
 - (2b) Player 1 either accepts the offer to end the game or rejects the offer to continue the game.
 - (3) In the third period, player 1 receives a share s of the dollar, leaving $1 - s$ to player 2.

Application: Sequential Bargaining Game

- Let $s_1(3) = s$ and $s_2(3) = 1 - s$.
- In general, in period t , $s_1(t)$ and $s_2(t)$ are offered to players 1 and 2. The offers satisfy

$$s_1(t) + s_2(t) = 1.$$

- The **present value (现值)** of payoff to player i is $\delta^{t-1}s_i(t)$ if the bargaining is ended in period t .
- We use backwards induction to solve the game.

Application: Sequential Bargaining Game

- In the second period, player 2 is at the move. Because the payoff to player 1 in period 3 is s , player 2 will offer $s_1(2) = \delta s$ to player 1 and $s_2(2) = 1 - \delta s$ to himself. Player 1 accepts the offer.
- In the first period, player 1 will offer $\delta(1 - \delta s)$ to player 2 and $1 - \delta(1 - \delta s)$ to himself, and player 2 will accept the offer. Then, the game ends.

Application: Sequential Bargaining Game

- The backwards-induction outcome of the three-period bargaining game:
- Player 1 offers the settlement

$$\begin{aligned}s_1^*(1) &= 1 - \delta(1 - \delta s), \\ s_2^*(1) &= \delta(1 - \delta s).\end{aligned}$$

- Player 2 accepts the offer, and the game ends.

- 1 Introduction
- 2 Games of perfect information
 - Backwards Induction
 - Stackelberg Model of Duopoly
- 3 Games of imperfect information
- 4 Extensive-form representation
- 5 Subgame-perfect Nash equilibrium
- 6 Summary**

Summary

- We have considered dynamic games of complete information.
- Two basic questions:
 - 1 How to describe a dynamic game \rightarrow extensive-form representation (information set)
 - 2 How to solve a dynamic game? Why to introduce SPE?
- Backwards induction vs. SPE.